



POSPAC UAV

NOW WITH POST-PROCESSED CENTERPOINT® RTX™ SERVICE

POSPac UAV is Applanix' industry-leading differential GNSS-aided inertial post-processing software for georeferencing data from the Trimble APX series of board sets flying on small UAVs. POSPac UAV turns your UAV into a low-cost, highly efficient, professional grade mapping solution compatible with cameras, LiDAR and other mapping sensors.

DIRECT GEOREFERENCING FOR UNMANNED AERIAL VEHICLES

POSPac UAV coupled with a Trimble APX UAV GNSS-inertial system delivers the benefits of Direct Georeferencing to aerial surveyors flying small UAVs:

- ▶ Achieve high accuracy position and orientation ready for map production, minutes after data collection
- ▶ Eliminate or reduce the need for Ground Control Points
- ▶ Fly less sidelap for greater efficiency
- ▶ Map inaccessible and dangerous areas remotely with lower cost

WHY POST-PROCESSING?

POSPac UAV post-processing produces a higher accuracy and more robust georeferencing solution that can be generated in real-time, all within minutes of flying.

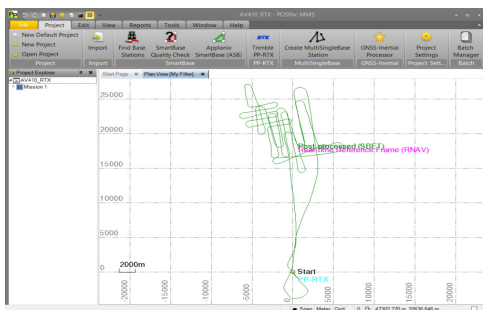
- ▶ It uses "gap-free" dedicated base station data or that from a CORS service instead of corrections over a radio link that can be jammed or interrupted.
- ▶ It uses the inertial data to bridge outages in the rover GNSS receiver data to ensure a continuous, gap free position and orientation solution.
- ▶ It improves the accuracy of both the position and orientation (especially heading), by running the data forward and reverse in time.
- ▶ Map without base stations using PP-RTX subscription service

INDUSTRY LEADING SOFTWARE

- ▶ POSPac UAV is integrated with Applanix' industry leading IN-Fusion™ GNSS-Aided Inertial processing technology for:
 - robust, centimeter level position and orientation information worldwide without reference stations
 - maintaining full accuracy before and after GNSS outages
 - no restriction on minimum number of satellites
 - fly turns without limiting bank angles => faster turns
- ▶ POSPac UAV also includes Applanix SmartBase Cloud for generating a set of observations for a virtual base station exactly where and when you need it, and emails it to your inbox ready for Differential GNSS processing (where available)

YOUR BENEFITS

- ▶ Reduced acquisition costs
- ▶ Reduced re-work costs with "know before you go" in field quality control
- ▶ Faster production
- ▶ Better accuracy
- ▶ Increased utilization



For more information, visit:
www.applanix.com/products/dg-uavs

Key Features

- ▶ Cm-level post-processed DGNSS position accuracy
 - removes the need for Ground Control Points in aero-triangulation (AT)
 - achieve cm level accuracy in LiDAR point cloud
- ▶ Accurate GNSS position translation from Antenna Phase Center (APC) to sensor origin
 - eliminates the need to estimate offset in AT which results in better accuracy
 - obtains cm level accuracy in LiDAR point cloud
- ▶ High accuracy orientation
 - strengthens the geometry in the AT block which reduces or eliminates sidelap
 - obtains cm level accuracy in LiDAR point cloud
- ▶ Speeds up processing time of AT by improving point matching success and blunder detection
- ▶ 200 Hz Georeferencing solution
 - filters out bad GNSS observables
 - improves heading accuracy
 - reduces interpolation errors to sensor sampling times
- ▶ Automatically survey in dedicated base stations direct from POSPac using Trimble CenterPoint® RTX™
 - streamline map production workflow
- ▶ Full transformation support
 - user selectable datums and projections
 - transformation to camera Exterior Orientation
- ▶ PP-RTX available
- ▶ LiDAR QC Tools included
 - Boresight calibration
 - LiDAR-based Corrected SBET trajectory
 - Point Cloud generation